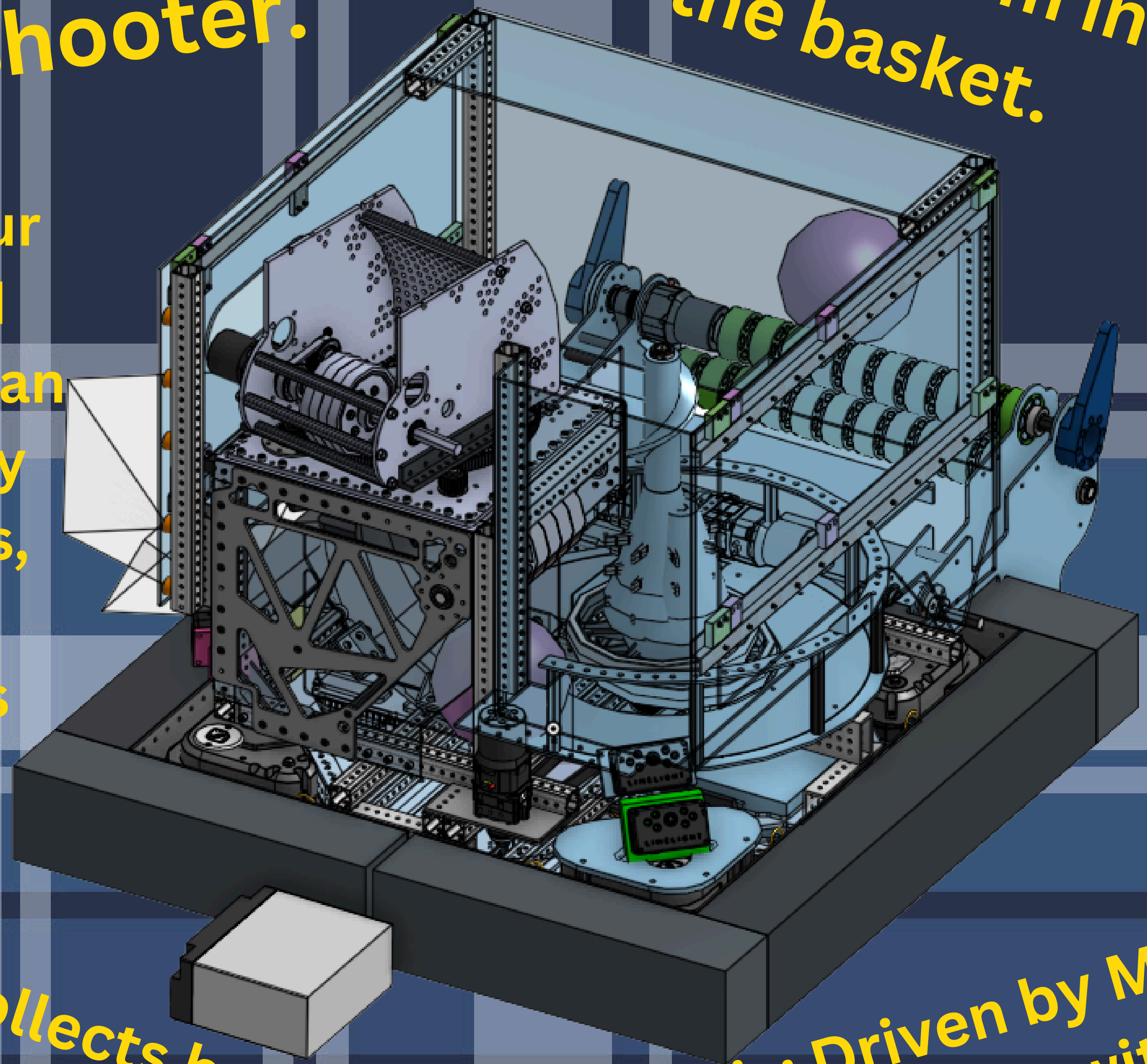


# Jungle Jim

**Indexer:** Feeds balls into the spindexer, which then moves them into the shooter.

**Shooter:** Receives balls from the spindexer and launches them into the basket.

Because of our turret based shooting, we can automatically aim our shots, even during autonomous mode.



**Intake:** Collects balls and feeds them into the indexer via a 3D-printed ramp and our flywheels.

**Chassis:** Driven by MK5 swerve drive's with limelight cameras mounted on the sides